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Characterisation of an ultrasonic transducer connected to quarter and full wavelength horns

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Ultrasonic scaling device

Photron fastcam ultima APX

Recording

Frame rate: 500fps Resolution: 1024x1024 N° of frames: 963

Video

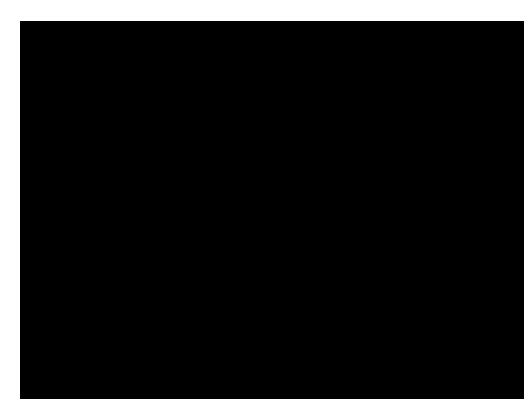
Frame rate: 30fps

Mectron dental transducer with PS1 scaling insert





Ultrasonic cutting device



Mectron dental transducer with OT7 cutting insert

Photron fastcam ultima APX

Revoratingcut in Frame Rate: 4000fps Resolution: 512x512

Video Frame rate: 1000fps



Aim of Research

To create design criteria for stable power ultrasonic systems through understanding sources and causes of nonlinear behaviour

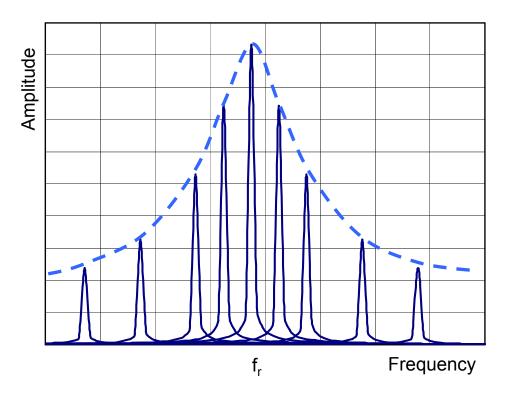


Linear response of ultrasonic devices

Excitation at individual frequencies

Continuous / burst swept sine wave

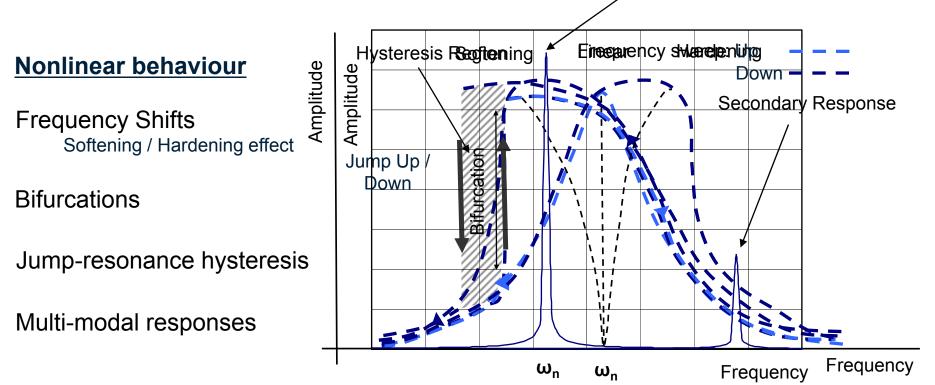
Low excitation levels





Nonlinear responses of ultrasonic devices

Can significantly influence driving stability as well as hindering power ultrasonic system development





Source of nonlinear behaviour

Nonlinear behaviour is directly influenced by:

Application of high stresses

• High vibration amplitudes

Dielectric, mechanical and piezoelectric losses within piezoceramics

- Temperature increases
- High electric field

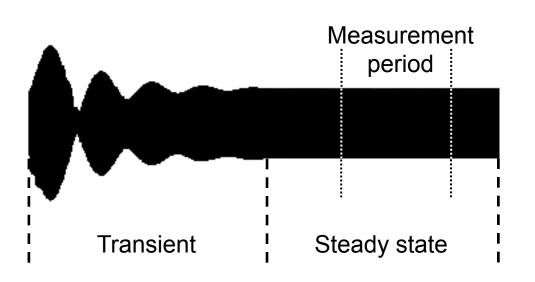
To understand nonlinear characteristics of the full ultrasonic device

• Remove thermal contributions from piezoceramics



Removal of thermal effect

Burst sine sweep technique



<u>Burst</u>

- 6000 cycles
- At 28kHz; 0.286 sec
- Time delay; 1-10 sec



Transducer & rodhorns



Mectron Transducer

	Length of rod (mm)	
	1⁄4 λ	Full λ
Aluminium	16	95
Brass	13	60
SS	13	110



Aluminium 6082



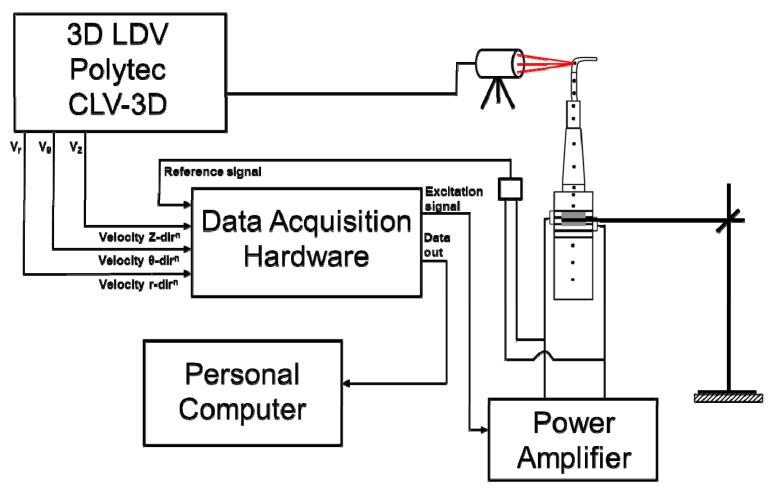




Stainless Steel 316



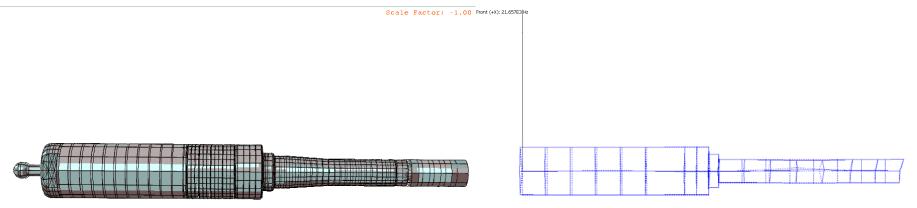
Experimental Modal Analysis





Design of rod horns: tuned mode

Quarter wavelength brass rod horn:



ODB: FirstLongBrass1305024328.296.odb Abaqus/Standard Version 6.7-1 Thu Feb 25 17:28:13 GMT Standard Time 2010

Step: Frequency Step Mode 6: Value = 2.71173E+10 Freq = 26209. (cycles/time) Deformed Var: U Deformation Scale Factor: +3.000e-03

Amp: 0.5, Dwell: 9 Persp: 0





, **"**,



Design of rod horns: tuned mode

Full wavelength brass rod horn:

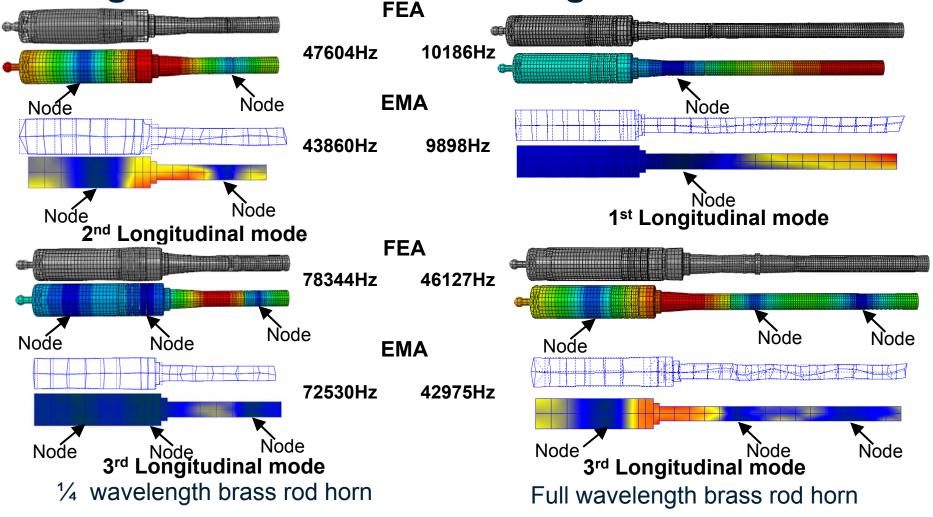
	Scale Factor: -1.	00
		Top (+2): 31.89%3 Hz
æ		
	ODB: SecondLongBrass1305025662.187.odb Abaqus/Standard Version 6.7-1 Thu Feb 25 19;45:00 GMT Standard Time 2010	
vX	Step: Frequency Step Mode 8: Value = 2.76515E+10 Freq = 26465. (cycles/time) Deformed Var: U Deformation Scale Factor: +3.000e-03	Amp: 0.5, Dwel: 9 Persp: 0





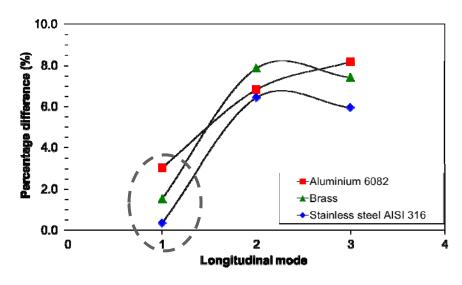


Design of rod horns: other longitudinal modes



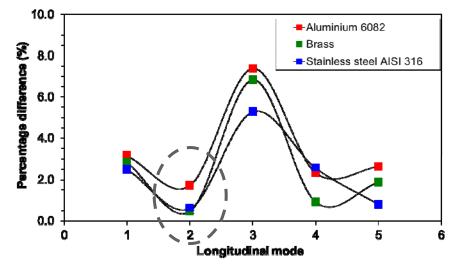


Percentage difference between FEA & EMA



Tuned mode: 1st longitudinal

1/4 wavelength rod horn



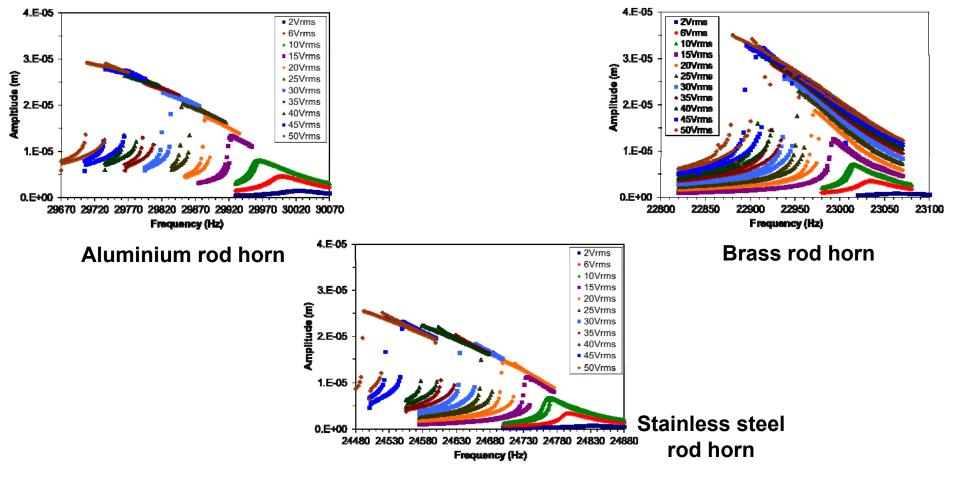
Tuned mode: 2nd longitudinal

Full wavelength rod horn



Nonlinear characterisation

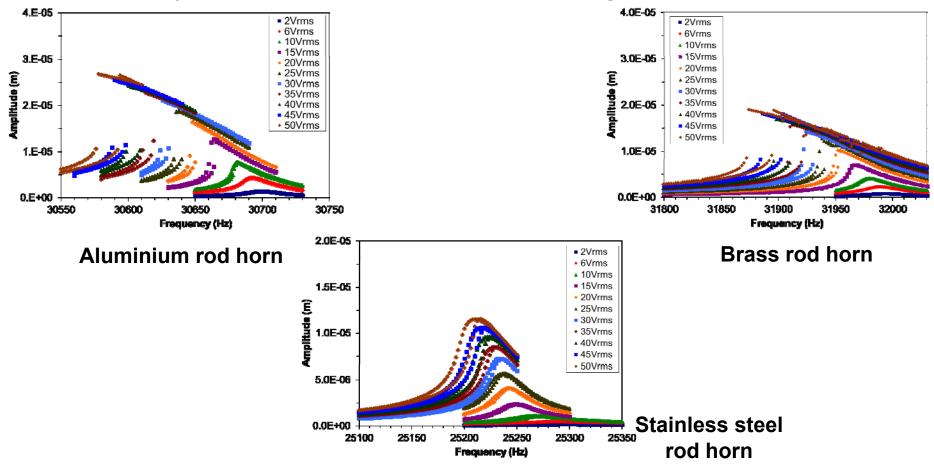
Frequency response plots: 1/4 wavelength rod horns





Nonlinear characterisation

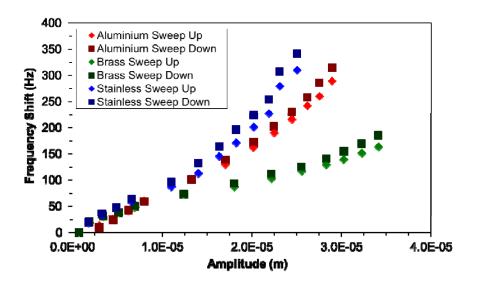
Frequency response plots: Full wavelength rod horn



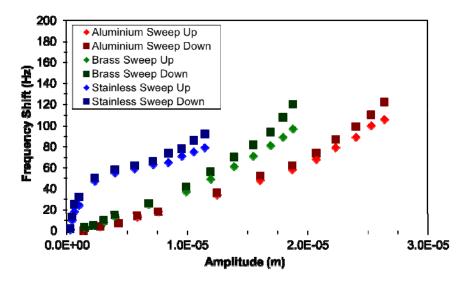


Nonlinear characterisation

Frequency shift against vibration amplitude



1/4 wavelength rod horns

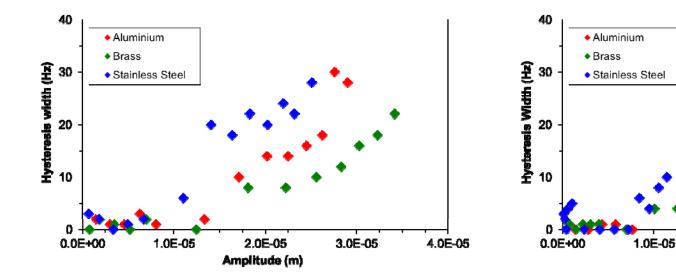


Full wavelength rod horns



Nonlinear characterisation

Hysteretic region width against vibration amplitude



1/4 wavelength rod horns

Full wavelength rod horns

2.0E-05

Amplitude (m)

3.0E-05

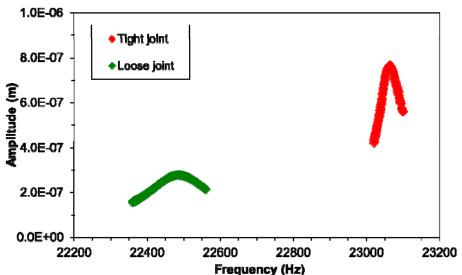
4.0E-05



Threaded joints

Joint tightness

- Resonant frequency
- Damping
- Enhanced acoustic transmission
- Reliability
- Ultimately dependent on tensile strength of material

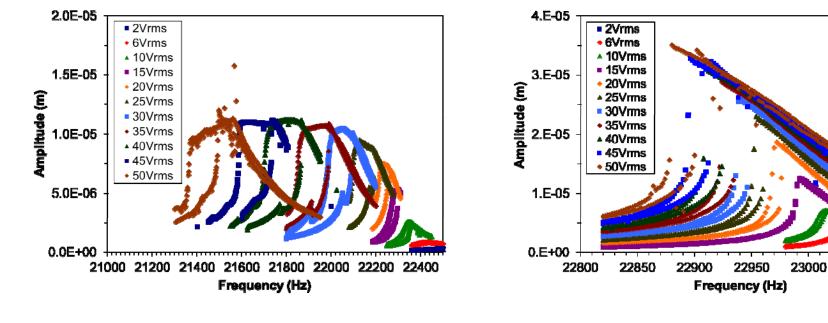


¹/₄ λ rod horn assembly with different joint tightness



Nonlinear characterisation: Joint tightness

Frequency response



Low Q_m rod horn assembly (looser joint) High Q_m rod horn assembly (tighter joint)

23050

23100



High Q

Low Q

4.0E-05

3.0E-05

Nonlinear characterisation: Joint tightness

100

80

60

40

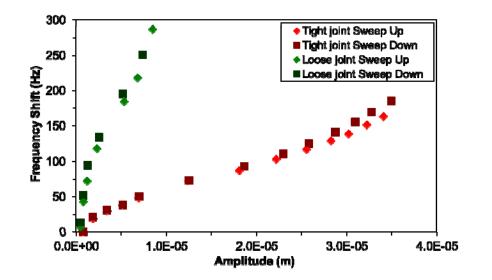
20

0

0.0E+00

1.0E-05

Hysteresis width (Hz)



Frequency shift against vibrational amplitude

Hysteretic region width against vibrational amplitude

2.0E-05

Amplitude (m)



Summary

- Correlation between FEA and EMA methods
 - Dependant on mode of vibration
- Characterisation of ¼ & full wavelength rod horns
 - Length of rod horn / mode of vibration
 - Material choice
- Joint tightness
 - Significant influence on nonlinear behaviours



Acknowledgements

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Engineering and Physical Science Research Council (EPSRC) Grant Nº: EP/E025811/1

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Equipment Mectron Medical Technology, Carasco, GE, Italy EPSRC Ione pool: High speed camera



Thank you for listening Questions?



And the weather forecast will generally be:

Sunny patches with heavy showers



Literature

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